## RCMB132-01

AC/DC sensitive residual current monitoring module for measuring AC and DC currents up to $\pm 100 \mathrm{~mA}$


## Intended use

The AC/DC sensitive residual current monitoring module monitors electrically earthed power supplies up to 300 V and connected loads up to nominal currents of 32 A for leakage and fault currents. The module is intended for installation in distribution equipment such as PDUs (Power Distribution Units), outlet boxes or multiple socket-outlets and is supplied with DC $12 \ldots 24 \mathrm{~V}$.

Any other use than that described in this document is regarded as improper.

## General safety instructions

Part of the device documentation in addition to this manual is the enclosed "Important safety instructions for Bender products".

Installation, connection and commissioning are to be carried out by electrically skilled persons only! It is essential to follow the existing safety instructions.


Danger! Risk ... . This signal word indicates that there is a high risk of danger that will result in death or serious injury if not avoided.

1 This symbol refers to information that is designed to help you make the best use of the product.

## Scope of delivery

- 1 RCMB132-01
- 2 four-pole plugs (Phoenix Contact, PTSM 0.5/4-P-2.5)
- 1 cover plug for protecting an open socket


## Device features

- AC/DC sensitive leakage and fault current monitoring for preventive maintenance
- High resolution for implementing equipment leakage current monitoring
- Measured value and alarm transmission via Modbus RTU (RS-485)
- Frequency range DC... 2 kHz
- Compact design for monitoring nominal loads up to $I_{\mathrm{n}}=32 \mathrm{~A}$
- Low load current sensitivity due to fully shielded measuring current transformer
- Continuous monitoring of the connection to the measuring current transformer
- Integrated test function
- Supply voltage DC $12 . . .24 \mathrm{~V}$


## Functional description

The RCMB132-01 is used to measure residual currents and output the values via an interface. The residual current monitoring module measures both AC and DC currents. The RMS value is calculated from the DC component included in the residual current and the AC component below 2000 Hz . The RCMB132-01 continuously checks the connection of the internal measuring current transformer.

## Via the RS-485 interface:

- a signal proportional to the RMS value is transmitted (measured value update every 180 ms )
- alarm messages are signalled
- response values are configured
- a functional test can be started

The existing switching outputs S1 and S2 switch to alarm state when the set response value is exceeded or a malfunction occurs.

1 When S2 (RMS) switches, S1 (DC) is also switched simultaneously.

## Dimension diagram



All dimensions in mm

## Installation and connection

Risk of an electric shock!
Existing protective conductors and low-resistance conductor loops must not be routed through the measuring current transformer! Otherwise, high currents could be induced into the conductor loop due to the AC/DC sensitive measuring technology used.
1 The standard Modbus address of the monitoring module is 100 . If several monitoring modules are installed in a system, the Modbus addresses should be set on the bus before common commissioning.
1 Primary conductors must be insulated in such a way that they fulfil the function of basic insulation for the rated voltage.

## DIN rail mounting

Mounting with mounting foot MCCT20 (accessories, refer to ordering details)

(49)

## Pin assignment

|  | Pin | Name | Description |
| :---: | :---: | :---: | :---: |
|  | X1, Y1 | VCc | Supply voltage (DC 12...24V) |
|  | X2, Y2 | GND | Ground |
|  | X3, Y3 | B | RS-485-B |
|  | X4, Y4 | A | RS-485-A |
|  | Z5 | S1 | Switching output 1 (DC) |
|  | Z6 | S2 | Switching output 2 (RMS) |

The two four-pole connectors $\mathbf{X}$ and $\mathbf{Y}$ are designed as combinations of socket and plug, the twopole connector $\mathbf{Z}$ is designed as push-in terminal.

## Wiring diagram (example)



* Terminating resistor $120 \Omega$ must only be set on the last device in the RS-485 bus chain
** An external protective circuit is especially required for inductive loads.

$!$
The maximum cable length must be limited to $\leq 10 \mathrm{~m}$.

## Timing diagram "Functional test"

As soon as it is recognised that register 4000 has the value 0 , the time measurement starts with $t=0$.
M1... 3 in the timing diagram are the points in time at which a higher-level control can and should check during the functional test that the switching outputs S1... 2 actually switch independently of each other. Possible causes for a failed functional test:

- S... is permanently connected to GND
- S... is permanently connected to Vcc
- Short circuit between S1 and S2


Frequency response at response value $I_{\Delta}=\mathbf{3 0} \mathbf{~ m A}$


Dashed line: $I_{\Delta}$ (response value)
Green: $I_{\Delta}$ (measured value)

## Modbus register overview

Supported function codes:

| $0 \times 03$ | Read Holding Registers |
| :--- | :--- |
| $0 \times 04$ | Read Input Registers |
| $0 \times 06$ | Write Single Register |
| $0 \times 10$ | Write Multiple Registers |

Properties of the registers:

| RO | Read Only |
| :--- | :--- |
| WO | Write Only |
| RW | Read and Write |

"Broadcast" (address "0"): Execute action, do not send a response. Broadcast only works with "write" commands.

1 If there is more than one slave on the bus, a change of the bus address must not be triggered by broadcast under any circumstances.

1 If a new parameter value is stored during a write access, the response of the monitoring module is delayed for a maximum of 55 ms due to the internal storage process. No Modbus communication is possible during this time. In the event of multiple write accesses (function code 0x10, Write Multiple Registers), the times are added up.

## Measured values and statuses

| Register | Property | Description | Format | Description/unit | Range |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 2000 | RO | Measured value $I_{\triangle \text { n } \mathrm{RNS}}$ | UINT16 | $x 0.1 \mathrm{~mA}$ | 0... 1000 |
| 2001 | RO | Measured value $I_{\triangle n D C}$ | UINT16 | $\times 0.1 \mathrm{~mA}$ | 0... 1000 |
| 2002 | RO | Status word ${ }^{1)}$ | UINT16 | Bit | 0...0xFFFF |
| 2003 | R0 | Status word 2 ${ }^{2)}$ | UINT16 | Bit | 0...0xFFFF |
| 2004 | RO | Application software version | UINT16 | $103 \mathrm{dez}=\mathrm{V} 1.03$ | 0...0xFFFF |
| 2005 | RO | Communication API version | UINT16 | $256 \mathrm{dez}=\mathrm{V} 2.56$ | 0...0xFFFF |
| 2006 | RO | Software version | UINT16 | 604 = D0604 | 0... 65535 |
| 2007 | Reserved |  |  |  |  |
| 2008 | Reserved |  |  |  |  |
| 2009 | R0 | Serial number | UINT32 | HiWord | $0 \ldots . .232-1$ |
| 2010 |  |  |  | LoWord |  |
| 2011 | RO | Max. measured value $I_{\text {In RMS }}{ }^{3 /}$ | UINT16 | $\times 0.1 \mathrm{~mA}$ | 0... 1000 |
| 2012 | R0 | Max. measured value $I_{\text {An }}{ }^{3}{ }^{3}$ | UINT16 | $\times 0.1 \mathrm{~mA}$ | 0... 1000 |
| 2013... 2999 | Reserved |  |  |  |  |

[^0]
## ${ }^{1)}$ Status word 1

| Status byte | Bit | Meaning | Value |
| :---: | :---: | :---: | :---: |
| 1 | Bit 0 | Status ERR_OUT | $\begin{aligned} & 0=\text { error, deactivated } \\ & 1=\text { no error, activated } \end{aligned}$ |
|  | Bit 1 | Status S1 | $\begin{aligned} & 0=\text { off, deactivated, triggered } \\ & 1=\text { on, activated, not triggered } \end{aligned}$ |
|  | Bit 2 | Status S2 |  |
|  | Bit 3 | Reserved |  |
|  | Bit 4 | Result last functional test | $\begin{aligned} & 0=\text { no error } \\ & 1=\text { measured current too low } \end{aligned}$ |
|  | Bit 5... 6 | Reserved |  |
|  | Bit 7 | Common error | $\begin{aligned} & 0=\text { no error } \\ & 1=\text { error } \end{aligned}$ |
| 2 | Bit 8... 15 | Reserved |  |

## 2) Status word 2

| Status byte | Bit | Meaning | Value |
| :---: | :--- | :--- | :--- |
| 3 | Bit $0 \ldots 7$ | Reserved |  |
|  | Bit 8 | RMS measurement status | $0=R M S$ value $<$ response value <br> $1=R M S$ <br> value $>$ response value |
|  | Bit 9 | RMS measurement status | $0=D C$ value $<$ response value <br> $1=D C$ value $>$ response value |
|  | Bit $10 \ldots 15$ | Reserved |  |

## Parameters

1 Duration write access: 55 ms.
When writing, the old value is sent first. Only after this does the changeover to the new value take place.

| Register | Property | Description | Format | Description/unit | Range |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 3000 | RW | Response value $I_{\triangle n}$ RMS | UINT16 | $\begin{aligned} & \text { x } 0.1 \mathrm{~mA} \\ & \text { Example: } 300=30.0 \mathrm{~mA} \end{aligned}$ | 3.5... 100.0 mA |
| 3001 | RW | Response value $I_{\triangle n}$ DC | UINT16 |  |  |
| 3002 | RW | Bus address | UINT16 |  | 1... 247 |
| 3003 | RW | Baud rate | UINT16 |  | $\begin{aligned} & 0^{*}=19200 \mathrm{bps} \\ & 1=9600 \mathrm{bps} \\ & \hline \end{aligned}$ |
| 3004 | RW | Transmission mode | UINT16 |  | $\begin{aligned} & 0^{*}=1-8-\mathrm{E}-1 ; 1=1-8-0-1 \\ & 2=1-8-\mathrm{N}-2 ;(3=1-8-\mathrm{N}-1) \end{aligned}$ |
| 3005... 3999 | Reserved |  |  |  |  |

[^1]
## Control (test, reset, find module)

| Register | Property | Description | Format | Comment/Unit | Range |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 4000 | W0 | Test \& reset | UINT16 | Test $=$ approx. 2 s (see timing diagram) | ```0= start functional test without offset measurement 1 = start functional test with offset measurement 1 Loads must be switched off 2 = reset measurement 3= reset \muC``` |
| 4001... 4009 | Reserved |  |  |  |  |
| 4010 | W0 | Find module ${ }^{1)}$ | UINT16 | Flashing time of the LED in s | 1... 30 |
| 4011... 4019 | Reserved |  |  |  |  |
| 4020 | W0 | Reset to factory settings (FAC) | UINT16 |  | $\begin{aligned} & 0=\text { Reset registers } 3000 \ldots 3001 \text { to FAC } \\ & 1=\text { Reset registers } 3000 \ldots 3004 \text { to FAC } \end{aligned}$ |
| 4021... 4999 | Reserved |  |  |  |  |

${ }^{1)}$ Prerequisite: Each module has a unique bus address. When writing to register 4010, exactly one slave is addressed via its bus address and starts to flash quickly. Register content 4010 is the flashing period to be used for the search of this module.

## Special purpose

The following registers can be used for extended identification and addressing of the modules. The three possible functions are explained in the register description.

The value written to register 60000 "Selector" is used to select the action to be executed. It is always written "Selector + serial number + other data" (function code 0x10, Write Multiple Registers). Exception: Reading the serial number in $60001 . . .60002$ with function code 0x03 (Read Multiple Registers).

| Register | Property | Description | Format | Comment/Unit | Range |
| :---: | :---: | :--- | :--- | :--- | :--- |
| 60000 | W0 | Selector 1) | UINT16 |  | $0=$ find module <br> $1=$ set new bus address |
| $60001 \ldots 60002$ | RW $^{2)}$ | Serial number $^{3)}$ | UINT32 |  | $0 \ldots 3^{31-1}$ |
| 60003 | W0 | Data 1 | UINT16 | Selector in 60000 <br> determines content | Selector $=0$ : Flashing time LED <br> $1 \ldots 30$ s selector $=1:$ Bus address <br> $1 \ldots .247$ |
| $60004 \ldots 69999$ | Reserved |  |  |  |  |

${ }^{\text {1) }}$ Register 60000 can only be written together with the correct register content from $60001 \ldots 60003$. The three registers are used as an extension of the Modbus address and only the slave with matching Modbus address and serial number reacts.
${ }^{2)}$ Write: address a specific module
When writing together with register 60000 the factory-set serial number of the module from register 2009 is entered. It is considered an extension of the bus address, so that only the module with exactly this serial number reacts.

Read: query serial numbers of existing modules
When reading registers $60001 \ldots 60002$, each module responds with the specified Modbus address after a random delay time. If several modules have the same Modbus address, different delays avoid simultaneous responses (collisions lead to crc errors). The master must respect a timeout period of 700 ms for reading the serial number so that the last possible response can still be received correctly. During this time, the master stores all received responses.
${ }^{3)}$ The serial number cannot be changed. The write access only refers to the writing in blocks of registers $60000 \ldots 60003$ in order to change a Modbus address or to identify a module.

## 1. Trigger signalling if serial number is known ("Find module")

## Prerequisite:

The serial numbers of the modules are known.
If the same bus address is assigned to several modules (e.g. because the factory address settings have not been changed yet), the known serial number can be used to control an LED and thereby identify the module.
1 A broadcast request can also be sent to make a module with a known serial number (but unknown Modbus address) flash.

## Master request

| Function code | $0 \times 10$ | 1 byte |  |
| :--- | :---: | :---: | :---: |
| Start address | 60000 | 2 bytes |  |
| Number of registers | 4 | 2 bytes |  |
| Byte count | 8 | 1 byte |  |
| Selector value | 0 | 2 bytes | Register 60000 |
| Serial number HiWord | Serial high | 2 bytes | Register 60001 |
| Serial number LoWord | Serial low | 2 bytes | Register 60002 |
| LED flashing time | Flashing time $(1 \ldots 30 \mathrm{~s})$ | 1 byte | Register 60003 |

## 2. Assign new bus address when the serial number is known

Prerequisite:
The serial numbers of the modules are known.
Each module must have its own Modbus address via which it can be addressed. If the addresses were not assigned during the setup phase and therefore several modules have the same address (factory setting: 100), the known serial number can be used as an extension of the Modbus addressing. Registers 60000... 60003 must be written together as a block. This way, only the module with matching bus address and serial number is addressed.

## Master request

1 A broadcast request can also be sent to assign a new Modbus address to a module with a known serial number (but unknown Modbus address).

| Function code | $0 \times 10$ | 1 byte |  |
| :--- | :---: | :---: | :---: |
| Start address | 60000 | 2 bytes |  |
| Number of registers | 4 | 2 bytes |  |
| Byte count | 8 | 1 byte |  |
| Selector value | 1 | 2 bytes | Register 60000 |
| Serial number HiWord | Serial high | 2 bytes | Register 60001 |
| Serial number LoWord | Serial low | 2 bytes | Register 60002 |
| New bus address | Bus address (1...247) | 1 byte | Register 60003 |

## 3. Identify several modules on the bus with the same address

The serial numbers of the modules are unknown.
If new Modbus addresses are to be assigned to modules, the serial numbers must be known. If the serial numbers are unknown, they must first be read out and assigned to the modules. In order for this to work even if Modbus addresses are assigned multiple times, the response of each module ( 9 bytes in total) is sent with a random delay. If there are several slaves with the same bus address, there is a certain probability that the responses will not collide and can be read by the master. If the master receives a correct response, it stores the response and waits for further responses until the timeout period ( 700 ms ) has elapsed.

If a new bus address is assigned to a correctly read serial number, this module can be excluded from a repeated request of the serial number.

## Master request

| Function code | $0 \times 03$ (or 0x04) | 1 byte |
| :--- | :---: | :---: |
| Start address | 60001 | 2 bytes |
| Number of registers | 2 | 2 bytes |

Technical data
Insulation coordination according to IEC 60664-1Primary circuitmonitored primary conductors
Secondary circuit Connections Vcc, GND, A, B, S1, S2
All following specifications apply to the insulation between theprimary and secondary circuitRated voltage300 V
Overvoltage category ..... III
Rated impulse voltage ..... 4 kV
Operating altitude ..... up to 3000 m AMSL
Rated insulation voltage ..... 320 V
Pollution degree ..... 2
Safe separation (reinforced insulation)
between primary and secondary circuitVoltage test acc. to IEC 61010-1AC 2.2 kV
Voltage supply
Supply voltage $U_{s}$... ..... DC 12... 24 V
Operating range of the supply voltage ..... $\pm 20$ \%
Ripple ..... 100 mV
Power consumption ..... $<0.75$ W
Measuring circuit
Internal diameter primary conductor opening ..... 15 mm
Measured value evaluation ..... DC, RMS
Measuring range $A C / D C \pm 300 \mathrm{~mA}$
Characteristics according to IEC 60755 . $A C / D C$ sensitive, type $B$$I_{\Delta n 1}$
Response valueDC $3.5 \ldots .100 \mathrm{~mA}(* 6 \mathrm{~mA})$
Response tolerance $0.7 . . .1 .0 \times I_{\text {An1 }}$
$I_{\Delta n 2}$Response valueRMS 3.5... 100 mA (* 30 mA )
Response tolerance
DC... 1 kHz ..... $0.7 \ldots 1.0 \times I_{\Delta n 2}$$1.0 \ldots 2.0 \times I_{\Delta n 2}$
Output range ..... $0 . . .100 \mathrm{~mA}$ (RMS)
Resolution. ..... $<0.2 \mathrm{~mA}$
Frequency range .DC... 2 kHz
Measuring time. ..... 180 ms
Operating uncertainty
DC. . 500 Hz $\pm(5 \%+0.5 \mathrm{~mA})$
$501 . . .1000 \mathrm{~Hz}$ ..... $\pm(15 \%+0.5 \mathrm{~mA})$
1... 2 kHz ..... $-(50 \% \pm 0.5 \mathrm{~mA})$
Time response
Response time $t_{\text {de }}$ (relay switching time of 10 ms considered) for $1 \times I_{\Delta n}$ ..... $\leq 290 \mathrm{~ms}$
for $2 \times 1$ In ..... $\leq 140 \mathrm{~ms}$
for $5 \times{ }_{1}$ n ..... $\leq 30 \mathrm{~ms}$
Recovery time tb ..... $\leq 2 s$
Disturbances
Load current $I_{n}$ ..... 32 A
Response value assignment
$I_{\Delta n 1}(D C)$ ..... S1
$I_{\Delta n 2}$ (RMS) ..... S2
Connection
Max. Cable length ..... $\leq 10 \mathrm{~m}$
Outputs
Interface ..... RS-485
Protocol ..... Modbus RTU
Switching outputs Open Collector, not short-circuit-proofSwitching capacity$40 \mathrm{~V} / 50 \mathrm{~mA}$
Output voltage LOW Ievel ..... 0...0.6 V
Output voltage HIGH level ..... 3.1...3.6 V
Hysteresis ..... $\leq 30 \%$
Environment/EMC ..... EMC
DIN EN IEC 62020-1:2021-10
....................... (IEC 62020-1:2020-04 Ed. 1.0), where applicableAmbient temperature (incl. primary conductorsrouted through module)$-25 \ldots+70^{\circ} \mathrm{C}$
Classification of climatic conditions acc. to IEC 60721
(related to temperature and relative humidity): Stationary use (IEC 60721-3-3) ..... 3K22
Transport (IEC 60721-3-2) ..... 2K11
Long-term storage (IEC 60271-3-1) ..... 1K22
Classification of mechanical conditions acc. to IEC 60271
Stationary use (IEC 60721-3-3) ..... 3M11
Transport (IEC 60721-3-2) ..... 2M4
Long-term storage (IEC 60271-3-1) ..... 1M12
Other
Operating mode continuous operation
Mounting ..... any position
Protection class ..... IP 30
Flammability class ..... UL94 V-0
Service life at $40^{\circ} \mathrm{C}$ ..... 10 years
Software ..... D0604
Plug (included in scope of delivery)

* $=$ factory settings


## Standards, approvals, certifications

The specified standards take into account the edition valid until 05.2024 unless otherwise indicated.

## EU Declaration of Conformity

The EU Declaration of Conformity is available at the following Internet address: https://www.bender.de/fileadmin/content/Products/CE/CEKO RCMB13x.pdf

## Ordering details

| Type | Measuring range | $U_{s}$ | Art. No. |
| :--- | :---: | :---: | :---: |
| RCMB132-01 | AC/DC $\pm 100 \mathrm{~mA}$ | DC 12 $\ldots 24 \mathrm{~V}$ | B94042136 |
| Mounting foot MCCT20 | B91080111 |  |  |

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[^0]:    ${ }^{3)}$ Maximum measured value since last reading of register 2000 or 2001

[^1]:    * $=$ factory settings

